

Improvement of resistive reach of distance protection through a power flow-based adaptive parameterization

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1. Introduction

Latest distance protection algorithms seek time performance improvements and sensitivity increase to detect all types of possible faults that may occur in the protected line. Adaptive algorithms improve in this sense the coverage of the distance protection against different types of faults in the electric network. However, to implement these algorithms in existing electrical substations (E/S) involves in most cases a considerable economic cost both to buy new protective relays neither change the firmware of existing ones.

This study develops an adaptive parameterization for distance protection based on the effect of pre-fault power flow in the apparent impedance locus. This adaptive application is integrated through a flexible operational logic to be implemented in many protection schemes currently used in E/S.

To mitigate the adverse effects of pre-fault power flow, settings criteria are presented for performing a selective coordination. These settings maximize the protection coverage by increasing the sensitivity for fault resistance in the protected line. The application restrictions over selectivity between protection zones of the distance relay are obtained by an algorithm that has been developed in order to analyze the performance of distance protection against three phase, double phase to earth and single phase to earth faults considering the pre-fault power flow and fault resistance expected in the protected line. This algorithm is based in the method of nodal matrix and its results have been compared with Fourier, Walsh and DEA (Differential Equation Algorithm) distance algorithm.

Conventionally, the protection parameters of distance relays have common values for both local and remote terminals of the protected line. However, through this adaptive parameterization each terminal has a different resistive reach depending on the direction of the line power flow, increasing the resistive faults coverage that could not be detected with conventional methods of distance coordination.

Keywords: distance protection, apparent impedance locus, R-X diagram, logical operation, resistive faults, adaptive distance protection.

2. Apparent impedance locus considering power flow in multiterminal networks

To simulate the effect of prefault power flow and fault resistance in the apparent impedance locus seen by the

relay it is important to consider a series of equivalences in a multiterminal network.

A. Effect of power flow in the protected line

It is demonstrate that the locus of the apparent impedance describe a circle if all parameters are kept fixed except the fault resistance. Moreover, the fact that the terminal is exporting or importing energy in prefault state modifies the apparent impedance locus seen by the relay and could lead to a loss of selectivity between protection zones.

The apparent impedance during a fault, considering the prefault power flow, is determined as follows

$$Z_R = m \cdot Z_l^+ + K_x \cdot R_f \quad (1)$$

where Z_R is the apparent impedance seen by the distance relay, m is the distance to fault in per unit of protected line length, Z_l^+ is the positive sequence impedance of the protected line, R_f represents the fault resistance and K_x is a multiplication factor whose value varies depending on the type of fault and the distance to fault. For a three phase fault, K_x is determined as follows

$$K_{3\phi} = \frac{Z_{rr}^+ + (m-1) \cdot Z_{pr}^+ - m \cdot Z_{qr}^+}{(Z_{rr}^+ + R_f) \cdot \left[\frac{N \cdot (1-m)}{(1-m) \cdot N + m} \right] - (1-m) \cdot (Z_{pr}^+ + R_f)} \quad (2)$$

for $0 < m < 1$

being $K_{3\phi}$ the multiplication factor for three phase faults, Z^+ the bus impedance matrix deduced for the electrical system under study and its subscripts p, q, r denotes the local terminal, remote terminal and point of fault in protected line, respectively. N is the prefault power flow indicator and is calculated as follows

$$N = \frac{E_p}{E_q} \quad (3)$$

where E_p and E_q are the local and remote voltage respectively.

For $m=0$, $K_{3\phi}$ is determined as

$$K_{3\phi} = \frac{Z_l^+}{(Z_l^+ + ZI_{qp}^+ + R_f) - \frac{(ZI_{pp}^+ + R_f)}{N}} \quad (4)$$

and, for $m=1$, $K_{3\phi}$ is deduced as follows

$$K_{3\phi} = \frac{Z_l^+}{N * (ZI_{qq}^+ + R_f) - (ZI_{pq}^+ + R_f)} \quad (5)$$

being ZI^+ the simplified bus impedance matrix once m fit the minimum or maximum value to avoid mathematical indetermination.

B. Programming for determining the apparent impedance locus

